

Adding Recursion to SPJRUD

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Complexity

- ▶ An algorithm **runs in $\mathcal{O}(f(n))$ time** if there exists a constant k such that on inputs of sufficiently large size n , the algorithm terminates after at most $k \cdot f(n)$ steps.
- ▶ An algorithm **runs in $\mathcal{O}(f(n))$ space** if there exists a constant k such that on inputs of sufficiently large size n , the algorithm uses at most $k \cdot f(n)$ bits of auxiliary memory.
- ▶ A **polytime algorithm** runs in $\mathcal{O}(n^k)$ time for some constant k .
- ▶ A **logspace algorithm** runs in $\mathcal{O}(\log n)$ space.
- ▶ Explain $\mathbf{L} \subseteq \mathbf{P}$: with $k \cdot \log n$ bits, you can use at most $2^{k \cdot \log n} = n^k$ distinct auxiliary states.

Query Evaluation

For every fixed SPJRUD expression E , we define $\text{EVAL}(E)$ as the following problem:

INPUT: A database \mathcal{I} and a tuple t .

QUESTION: Does t belong to $\llbracket E \rrbracket^{\mathcal{I}}$?

Proposition

For every expression E in SPJRUD, there exists a logspace algorithm for the following problem:

Given a database \mathcal{I} , return $\llbracket E \rrbracket^{\mathcal{I}}$.

\implies $\text{EVAL}(E)$ is in \mathbf{L} for every expression E in SPJRUD.

Fixed Points

Let U be a finite set. A mapping $f : \mathcal{P}(U) \rightarrow \mathcal{P}(U)$ is

- ▶ **inflationary** (French: *inflationniste*) if for all $X \subseteq U$, $X \subseteq f(X)$;
- ▶ **monotone** if for all $X, Y \subseteq U$, $X \subseteq Y$ implies $f(X) \subseteq f(Y)$.

A set $X \subseteq U$ is a **fixed point of f** if $f(X) = X$.

Example

Let $U = \{a, b\}$ and f_1, f_2, f_3 as follows.

X	$f_1(X)$	$f_2(X)$	$f_3(X)$
\emptyset	$\{a, b\}$	\emptyset	$\{a, b\}$
$\{a\}$	$\{a\}$	$\{b\}$	$\{b\}$
$\{b\}$	$\{b\}$	$\{a\}$	$\{a\}$
$\{a, b\}$	$\{a, b\}$	$\{a, b\}$	\emptyset

Fixed Point Computation

Property

Define $X^0 := \emptyset$, and for $i = 0, 1, \dots$, $X^{i+1} := f(X^i)$.

- ▶ If f is inflationary or f is monotone, then for some $n \leq |U|$, X^n is a fixed point.
- ▶ Moreover, if f is monotone, then this fixed point X^n is included in every other fixed point of f . That is, X^n is the unique least fixed point of f .

A Fixed Point Operator for SPJRUD

Let R and Δ be relation names s.t. $\text{sort}(R) = \text{sort}(\Delta) = \{A, B\}$.

Let

$$E := R \cup \pi_{AB} (\rho_{B \rightarrow C} (R) \bowtie \rho_{A \rightarrow C} (\Delta)).$$

Define f as the mapping s.t. for every relation X over $\{A, B\}$,

$$f(X) := \llbracket E \rrbracket^{\mathcal{I}_{\Delta \rightarrow X}}$$

Define $\Delta^0 := \emptyset$ and $\Delta^{i+1} := f(\Delta^i)$ for $i \geq 0$.

Questions

- ▶ Argue that f is both inflationary and monotone.
- ▶ Describe the fixed point reached by $(\Delta^i)_{i=0}^{\infty}$.

\implies New operator:

Syntax: $\mathbf{fp}_{\Delta:AB}(E)$

Semantics: $\llbracket \mathbf{fp}_{\Delta:AB}(E) \rrbracket^{\mathcal{I}}$ is the fixed point reached by $(\Delta^i)_{i=0}^{\infty}$.

Nesting is Allowed

Example

Let $\text{sort}(R) = \{A, B, C\}$.

$$E_1 := \mathbf{fp}_{\Delta:ABC} (R \cup \pi_{ABC} (\rho_{B \rightarrow D} (R) \bowtie \rho_{A \rightarrow D} (\Delta)))$$

$$E_2 := \pi_{AB} (E_1)$$

$$E_3 := \mathbf{fp}_{\Delta':AB} (E_2 \cup \pi_{AB} (\rho_{B \rightarrow C} (E_2) \bowtie \rho_{A \rightarrow C} (\Delta')))$$

Example

Let $\text{sort}(R) = \{A\}$.

$$\mathbf{fp}_{\Delta:A} (\Delta \cup (R - \mathbf{fp}_{\Delta':A} (\Delta' \cup (R - \Delta))))$$

Problem: $(\Delta^i)_{i=0}^\infty$ May Reach No Fixed Point

Let $\text{sort}(R) = \text{sort}(\Delta)$.

Let

$$f(X) := \llbracket R - \Delta \rrbracket^{\mathcal{I}_{\Delta \rightarrow X}}.$$

Questions

- ▶ Does f have a fixed point for every database \mathcal{I} ?
- ▶ Does f have a fixed point for some database \mathcal{I} ?
- ▶ What if we replace R with an arbitrary SPJRUD expression of the same sort as Δ ?



Proposition

The following problem is undecidable: Given an expression E that uses Δ , does $\Delta^0, \Delta^1, \Delta^2, \dots$ (as previously defined) reach a fixed point for every database \mathcal{I} ?

Solution

Alike in *Bases de Données I*:

domain independence is an undecidable semantic property \rightarrow safety is a decidable **syntactic** property

Proposition

Let $\mathbf{fp}_{\Delta:S}(E)$ be syntactically well-defined.

Let \mathcal{I} be any database, and $f(X) := \llbracket E \rrbracket^{\mathcal{I}_{\Delta} \rightarrow X}$.

Then,

if all **fp**-subexpressions¹ are
of the form $\mathbf{fp}_{\Delta':S'}(\Delta' \cup E')$ $\implies f$ is inflationary

and

if for every **fp**-subexpression
 $\mathbf{fp}_{\Delta':S'}(E')$, we have that E' is
positive in Δ' $\implies f$ is monotone

¹Since an expression is a subexpression of itself, these conditions apply also to $\mathbf{fp}_{\Delta:S}(E)$ itself.

SPJRUD+FP

SPJRUD+FP extends SPJRUD with the **fp**-operator, but with the following syntactic restriction:

whenever you write $\mathbf{fp}_{\Delta:S}(E)$, it must be the case that either

- ▶ E is of the form $\Delta \cup E'$, or
- ▶ E is positive in Δ .

Moreover, avoid mixing up both forms in a same expression (because in database theory, it is common to separate **ifp** from **lfp**, which correspond, respectively, to the first and second syntactic form).

Proposition

For every expression E in SPJRUD+FP, there exists a polytime algorithm for the following problem:

Given a database \mathcal{I} , return $\llbracket E \rrbracket^{\mathcal{I}}$.

\implies *EVAL(E) is in **P** for every expression E in SPJRUD+FP.*

Fixed Point Operator in Relational Calculus

Syntax We add formulas of the form

$$[\mathbf{fp}_{\Delta:x_1,\dots,x_k}(\varphi)](t_1,\dots,t_k)$$

where

- ▶ Δ is a k -ary relation name;
- ▶ x_1, \dots, x_k are the free variables of φ ; and
 \implies evaluating $\varphi(x_1, \dots, x_k)$ on some database $\mathcal{I}_{\Delta \rightarrow \Delta^i}$ results in a k -ary relation $\Delta^{i+1} := \{(c_1, \dots, c_k) \mid \mathcal{I}_{\Delta \rightarrow \Delta^i} \models \varphi(c_1, \dots, c_k)\}$
- ▶ every t_i is a constant or a variable.

The free variables of $[\mathbf{fp}_{\Delta:x_1,\dots,x_k}(\varphi)](t_1, \dots, t_k)$ are the variables that occur in t_1, \dots, t_k .

Semantics return all values for [the variables in] (t_1, \dots, t_k) that yield a tuple in the fixed point reached by $(\Delta^i)_{i=0}^{\infty}$ with $\Delta^0 = \emptyset$

Examples

- ▶ Transitive closure of a binary relation R .

$$\{\langle u, v \rangle \mid [\mathbf{fp}_{\Delta:x,y} (R(x, y) \vee \exists z (R(x, z) \wedge \Delta(z, y)))](u, v)\}$$

\implies all couples (u, v) in the transitive closure

- ▶ All nodes reachable from 0.

$$\{\langle v \rangle \mid [\mathbf{fp}_{\Delta:x,y} (R(x, y) \vee \exists z (R(x, z) \wedge \Delta(z, y)))](0, v)\}$$

- ▶ Is there a path from 0 to 4?

$$\{\langle \rangle \mid [\mathbf{fp}_{\Delta:x,y} (R(x, y) \vee \exists z (R(x, z) \wedge \Delta(z, y)))](0, 4)\}$$

- ▶ All couples not in the transitive closure.

$$\{\langle u, v \rangle \mid \exists w (R(u, w) \vee R(w, u)) \wedge \exists w (R(v, w) \vee R(w, v)) \wedge \neg [\mathbf{fp}_{\Delta:x,y} (R(x, y) \vee \exists z (R(x, z) \wedge \Delta(z, y)))](u, v) \}$$

Example

Let R be ternary relation name with $\text{sort}(R) = \{A, B, C\}$.

Let S be a unary relation name with $\text{sort}(S) = \{A\}$.

An R -tuple $\{A : p, B : q, C : r\}$ encodes the propositional formula

$$p \wedge q \rightarrow r.$$

An S -tuple $\{A : p\}$ encodes that p has truth value **true**.

Which propositions r must be true in every model of the formulas in R , given the truth values in S ?

$$\{r \mid [\mathbf{fp}_{\Delta:x} (S(x) \vee \exists p \exists q (R(p, q, x) \wedge \Delta(p) \wedge \Delta(q)))](r)\}$$

Syntactic Restrictions

$$[\mathbf{fp}_{\Delta: x_1, \dots, x_k}(\varphi)](t_1, \dots, t_k)$$

Question:

What syntactic restrictions on φ guarantee that

$$\emptyset = \Delta^0, \Delta^1, \Delta^2, \dots$$

will reach a fixed point?

Exercise

Let R be a binary relation that encodes a directed graph.
Which vertices are in the answer of the following query?

$$\{z \mid \underbrace{[\mathbf{fp}_{\Delta:x} (\exists y (R(x, y) \vee R(y, x)) \wedge \forall y (R(y, x) \rightarrow \Delta(y)))]}_{\wedge} (z) \wedge \exists x R(x, z) \}$$

Transitive Closure Logic

SPJRUD+TC adds a further restriction:

whenever you write $\mathbf{fp}_{\Delta:S}(E)$, it must be the case that $\text{sort}(E) = \vec{A}\vec{B}\vec{D}$ with $|\vec{A}| = |\vec{B}|$ and E computes, for every fixed \vec{D} -value \vec{d} , the transitive closure of the set of (\vec{A}, \vec{B}) -values that occur with \vec{d} ;

\implies if $\{\vec{A} : \vec{a}, \vec{B} : \vec{b}, \vec{D} : \vec{d}\}$ and $\{\vec{A} : \vec{c}, \vec{B} : \vec{c}, \vec{D} : \vec{d}\}$ are in the transitive closure, then so is $\{\vec{A} : \vec{a}, \vec{B} : \vec{c}, \vec{D} : \vec{d}\}$.

Note: separate transitive closure is computed for every value of \vec{D} .

Convenient notation: $\mathbf{tc}_{\vec{A};\vec{B}}(E)$

SPJRUD+TC has a lower complexity than SPJRUD+FP (**NL** versus **P**).

Discussion and Exercises

See course notes.